Octree-based Approach for Real-time Visualization of Surfaces Defined by Signed Distance Fields

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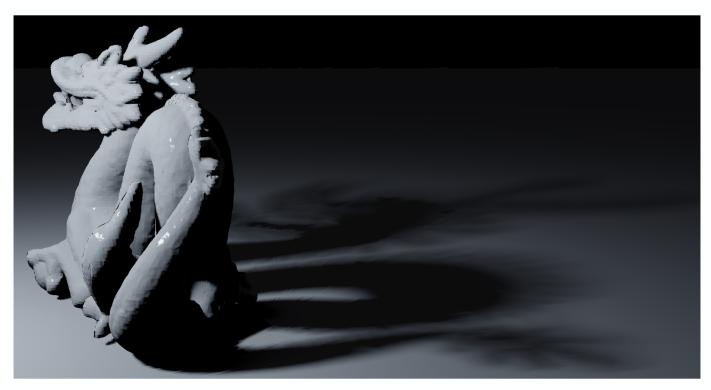
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MOTIVATION

- Real-time rendering engine
- Implicit representations of complex shapes
- Render engine is inefficient in rendering triangle lists



Rendering of mesh containing 871,414 triangles

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1 BACKGROUND





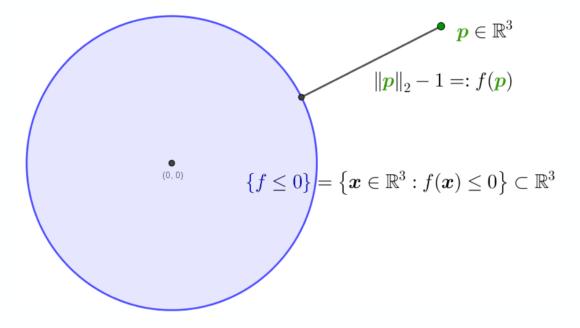
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SIGNED DISTANCE FUNCTION

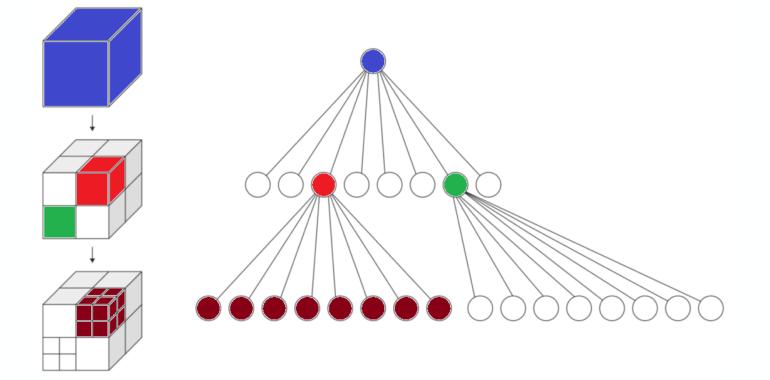


- f(p) is the distance from p to the surface
- Negative if inside, positive if outside
- Example:
 - Unit sphere: $f(p) = || p ||_2 1$

$$f(p) = \begin{cases} d(p, \partial \Omega), & \text{if } p \notin \Omega \\ -d(p, \partial \Omega), & \text{if } p \in \Omega \end{cases}$$

OCTREE

- Spatial data structure
- Eight children per node
- Much less memory footprint
- Quick access to SDF values
- High level of regularity
- GPU friendly



2 ALGORITHMS





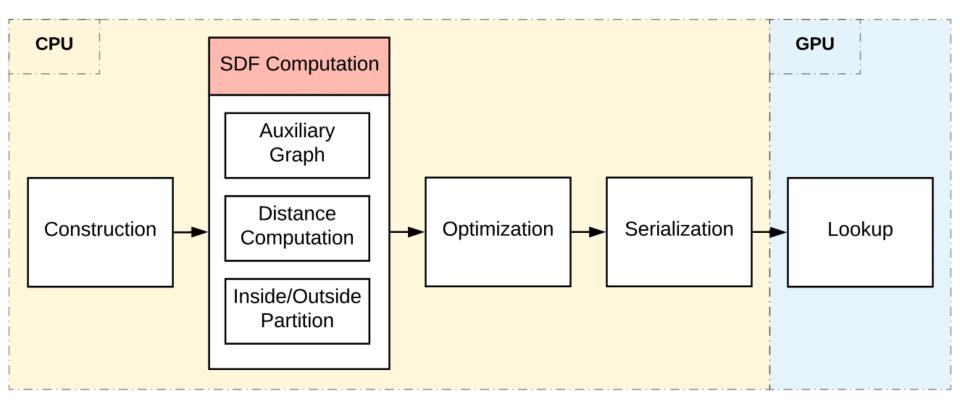
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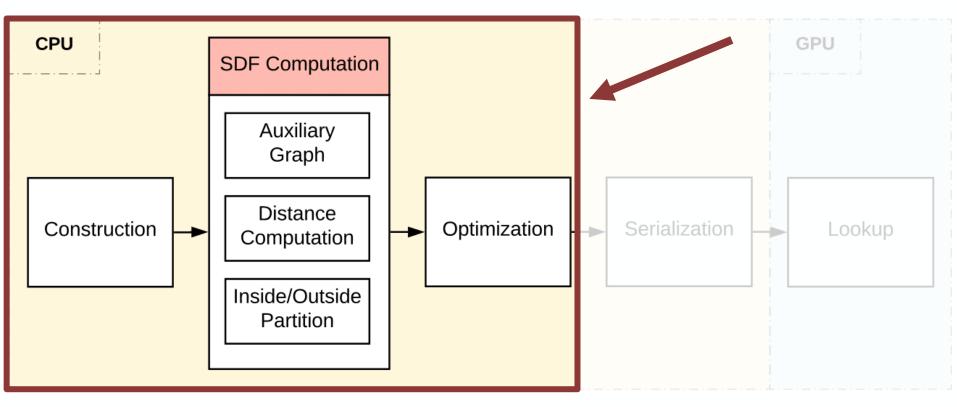
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ALGORITHMS WORKFLOW – SDF FROM TRIANGLE MESH



Workflow of octree algorithms following the natural order of execution

ALGORITHMS WORKFLOW – SDF FROM TRIANGLE MESH

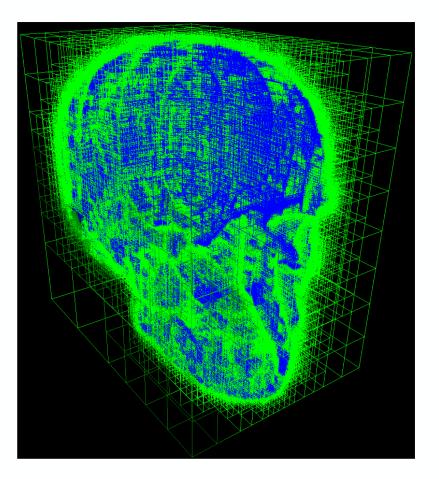


Workflow of octree algorithms following the natural order of execution

ALGORITHMS OCTREE CONSTRUCTION

Steps

- 1. Calculate root node's bounding box
- 2. Recursively create child nodes until:
 - 1. A depth limit has been reached
 - 2. The number of triangles is less than two
 - 3. Discretization error is negligible

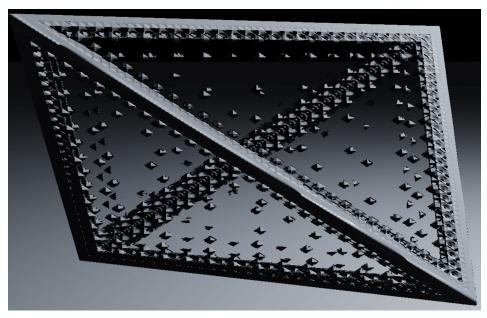


ALGORITHMS SDF COMPUTING

Steps

- 1. For every leaf's corner:
 - 1. Calculate SDF values for all nearby triangles
 - 2. Keep minimum

ALGORITHMS SDF COMPUTING



Without Inside/Outside Partition

With Inside/Outside Partition



ALGORITHMS SDF COMPUTING: INSIDE/OUTSIDE PARTITION

Auxiliary graph

- The graph is composed by a set of all node's corners in the octree
- Edges are all edges from all leaf nodes and their box diagonals
- Each vertex in the new graph has a confidence $-1.0 \le c \le 1.0$

ALGORITHMS SDF COMPUTING: INSIDE/OUTSIDE PARTITION

Auxiliary graph

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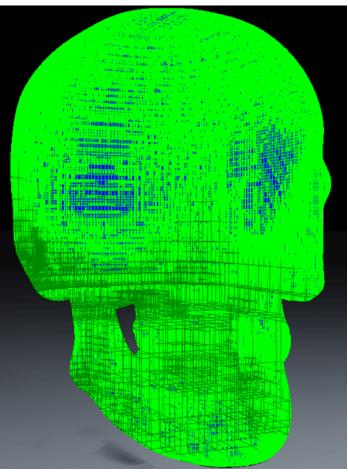
- The graph is composed by a set of all node's corners in the octree
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Confidence computing algorithm

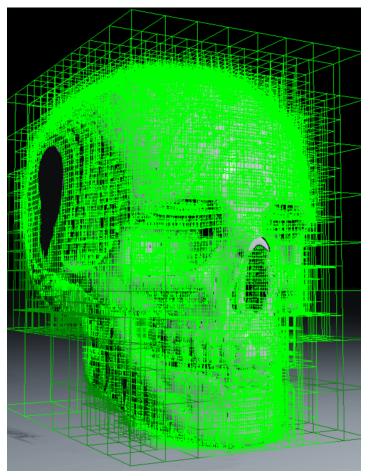
- Starting node: utmost negative corner, c = 1.0
- Priority queue hosts unprocessed nodes (highest confidence first)
- Confidence of a node = weighted average of neighbors' confidence

ALGORITHMS SDF COMPUTING: INSIDE/OUTSIDE PARTITION

Inside

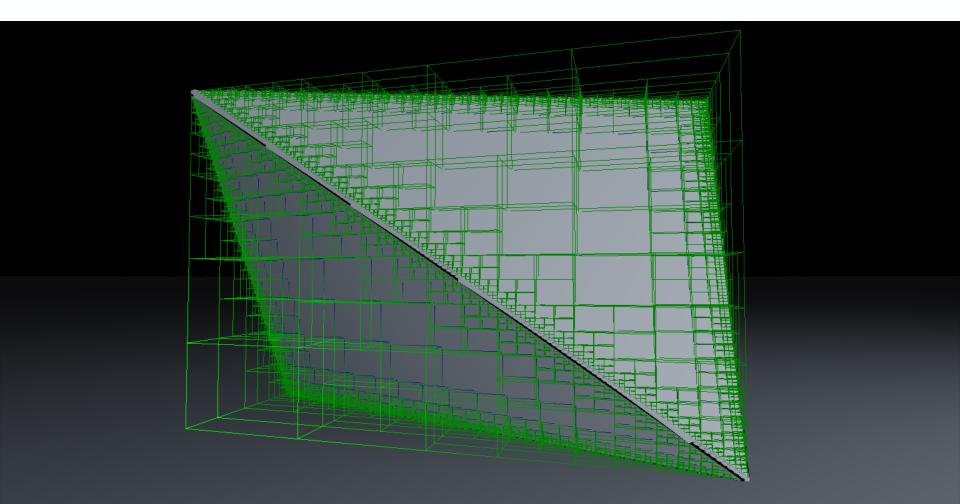


Outside



ALGORITHMS OCTREE OPTIMIZATION

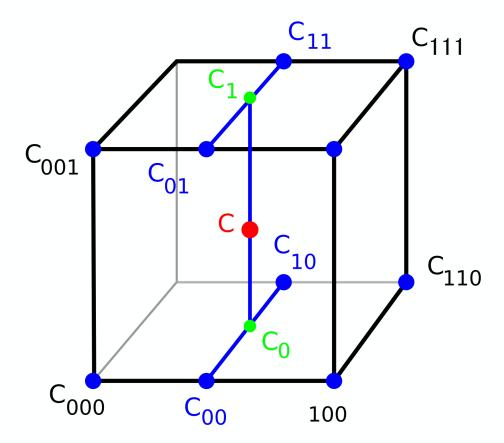
Number of nodes: 21.801



ALGORITHMS OCTREE OPTIMIZATION

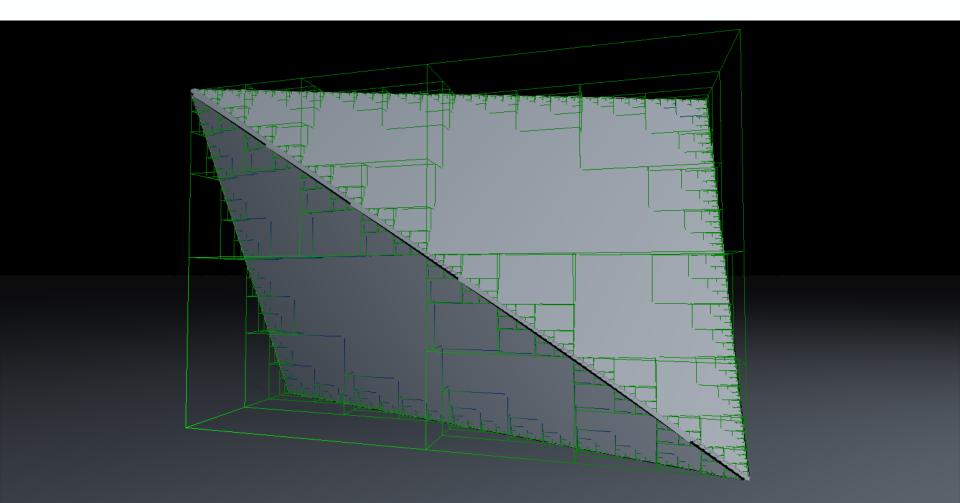
Adaptively Sampled Distance Fields (ADFs)

- Removes unnecessary child nodes
- Child nodes are removed if trilinear interpolation error is small



ALGORITHMS OCTREE OPTIMIZATION

Number of nodes: 10.825 (-50%)









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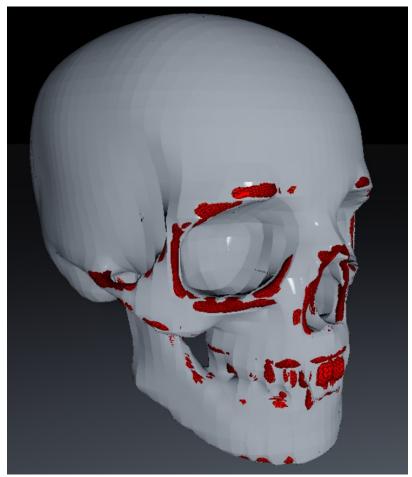
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RESULTS SDF vs TRIANGLE LIST

81.000 triangles

octree depth: 5

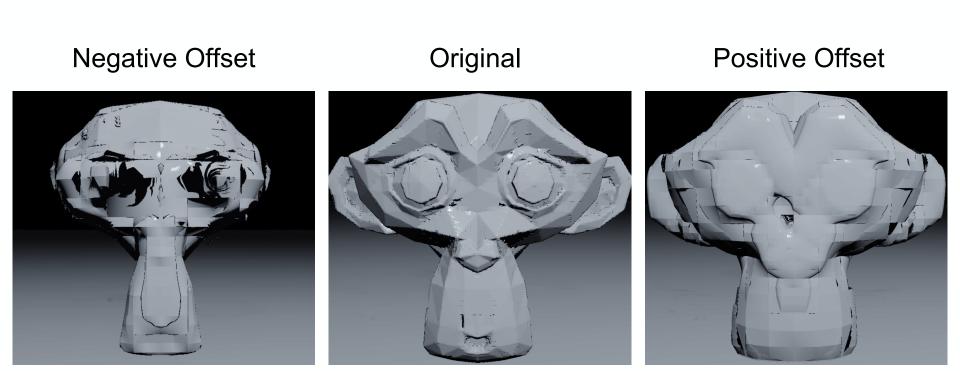


octree depth: 7



RESULTS OFFSET OPERATION

968 triangles, octree depth: 7



RESULTS SOFT SHADOWS

81.000 triangles, octree depth: 7



RESULTS SOFT SHADOWS

871,414 triangles, octree depth: 7



SUMMARY

- Octree construction from triangle mesh
- Novel solution for SDF computing and inside / outside partition
- Implicit representation allows offset and soft shadows. Other operations such as dilatation/erosion, and settheoretic operations can be executed efficiently.

FUTURE WORK

- More robust inside/outside partition and mesh correction
- Implement everything on the GPU
- Higher-order interpolations

THANK YOU FOR YOUR ATTENTION!



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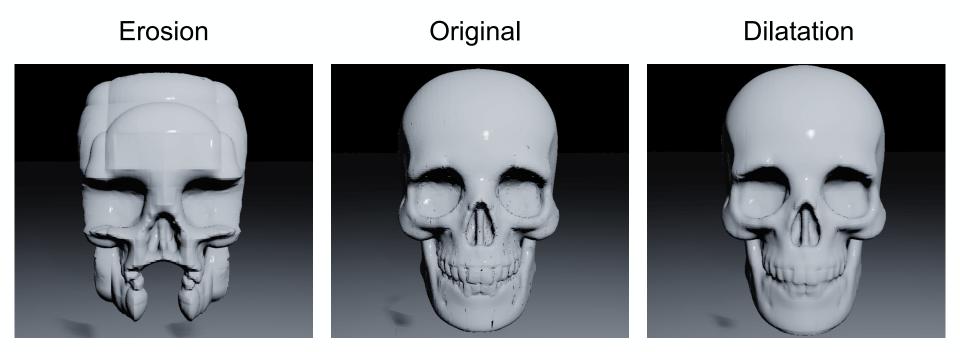
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EXTRA RESULTS DILATATION / EROSION OPERATIONS

81.000 triangles, octree depth: 7, d = 0.5



EXTRA RESULTS SET-THEORETIC OPERATIONS

968 triangles, octree depth: 7

